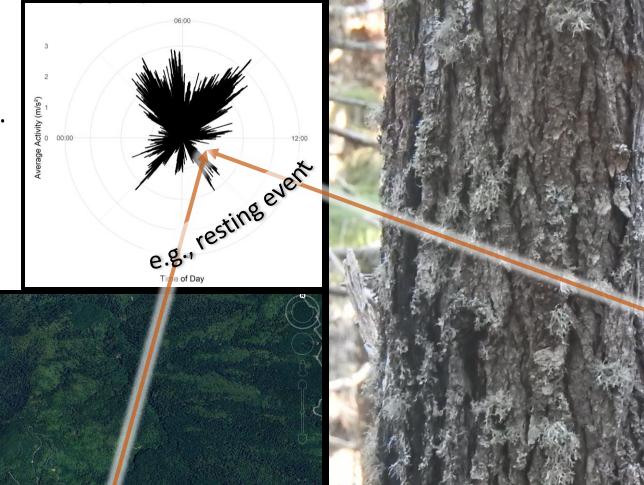


Resting areas must provide...

- Safety from predators
- Thermal refuge



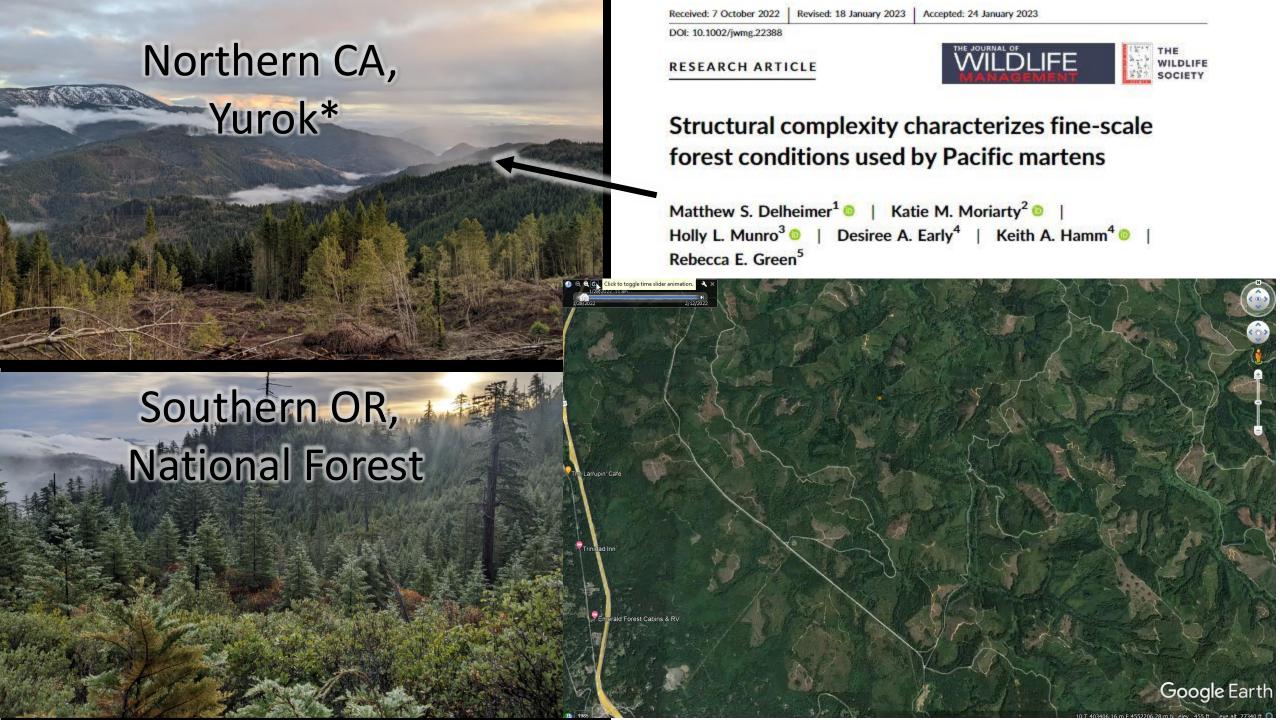




Finding these areas is hard!!

- Expensive
- Invasive







 Spatial GPS collar clusters -

Movement Ecology RESEARCH Identifying resting locations of a small elusive forest carnivore using a two-stage model accounting for GPS measurement error and hidden behavioral states

Dalton J. Hance^{1*}, Katie M. Moriarty², Bruce A. Hollen³ and Russell W. Perry¹

Telemetry

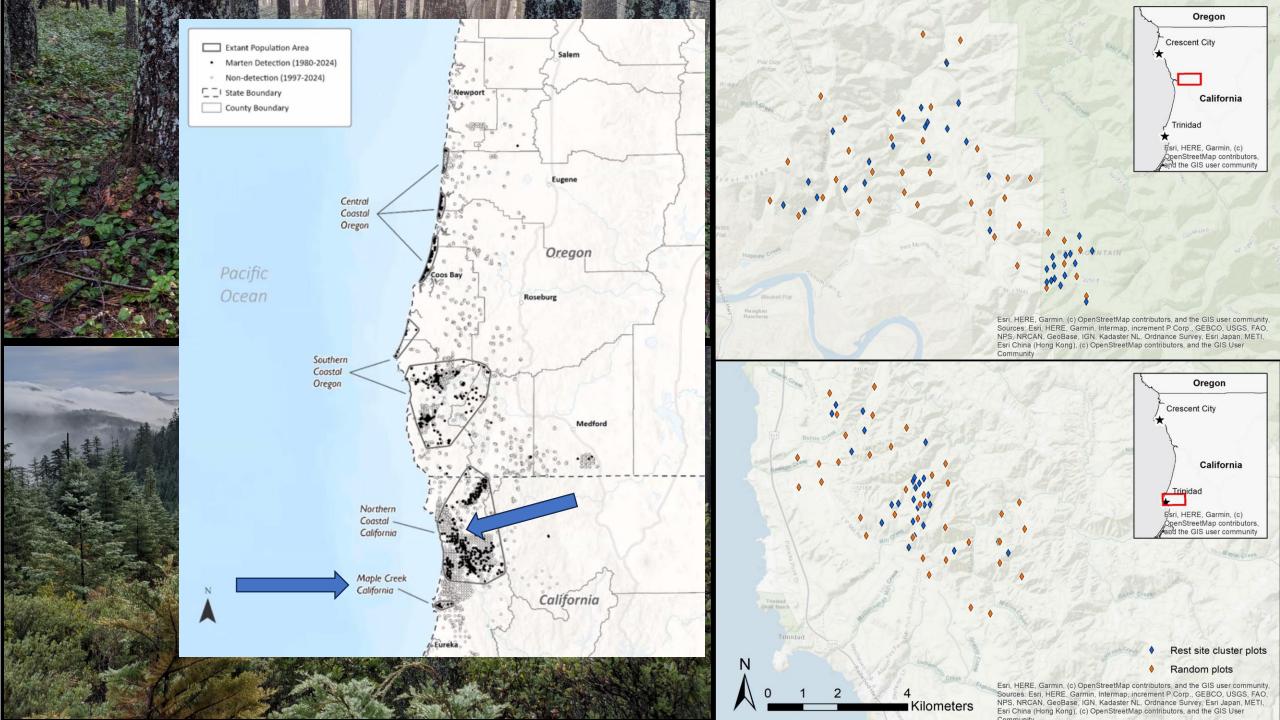




GPS collar location

- GPS collared 9 martens
- Identified 60 spatial
 GPS clusters
- With new design, identified 60 stratified random locations

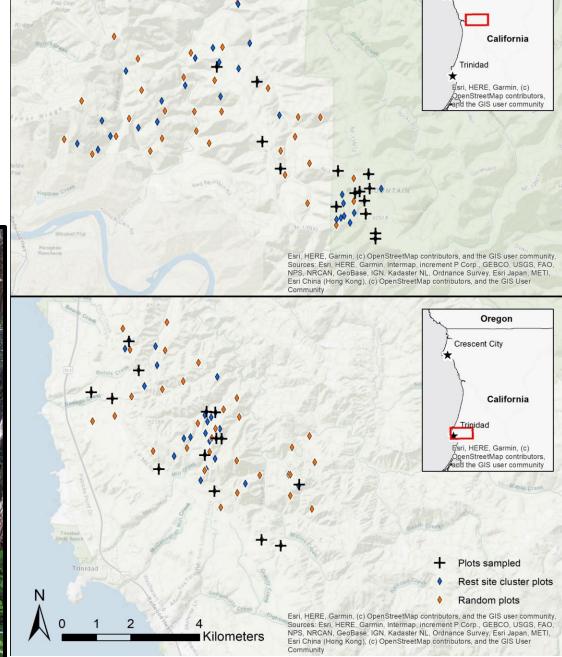




Collected vegetation data at 16 used and 13 random plots

Crew started June 10, 2025!



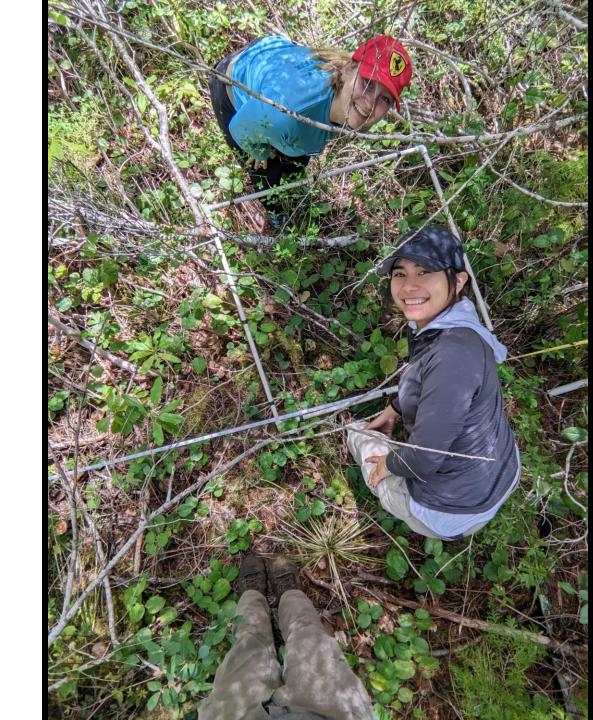


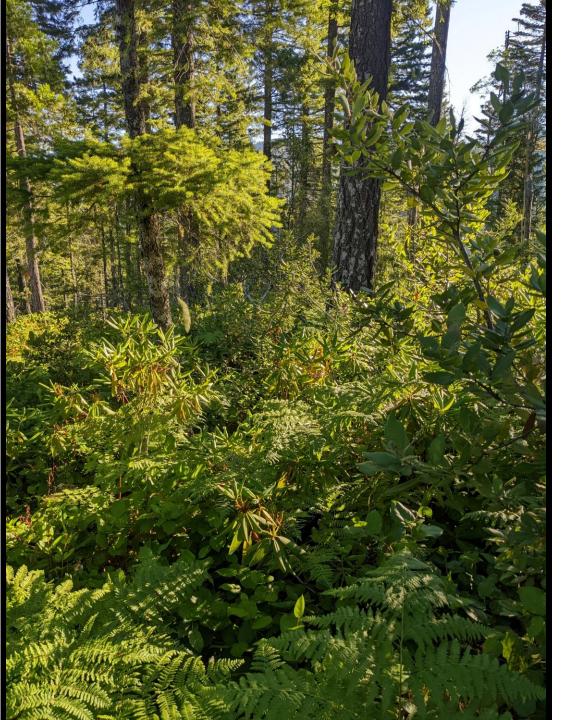
Crescent City

Collecting 40 vegetation metrics, including...

Plot metrics

- basal area (m²/ha)
- # live trees & snags
- % shrub cover
- visual obstruction (horizontal cover)
- large material
 - Logs and stumps
 - Slash and rock piles





How do I reduce fuel loads while maintaining marten resting habitat conditions here?

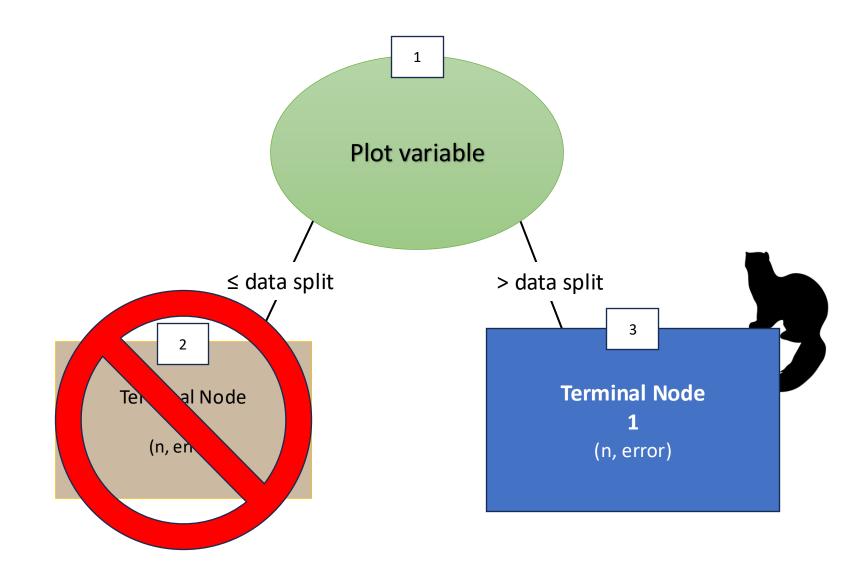


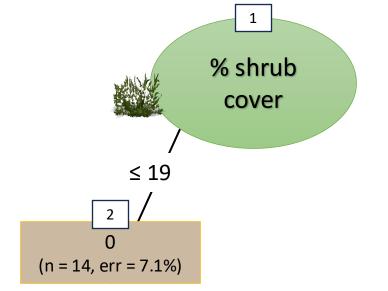


One example from Southern Oregon data

Building decision trees using:

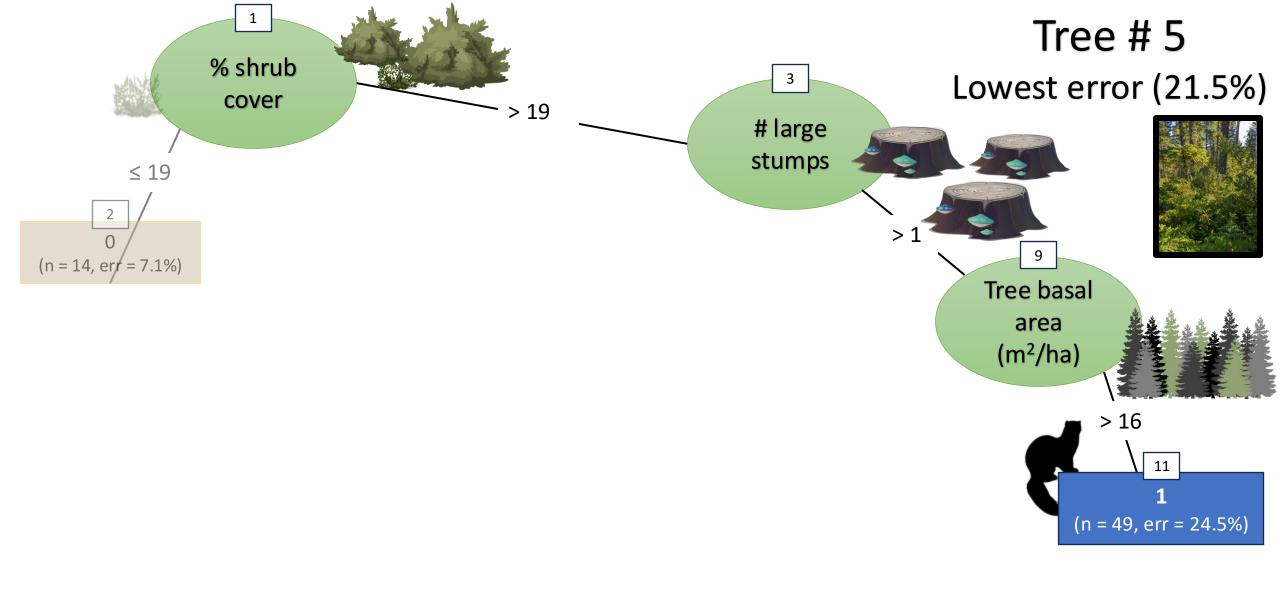
- Plot level vegetation data
- Boosted C5.0 algorithm via recursive partitioning

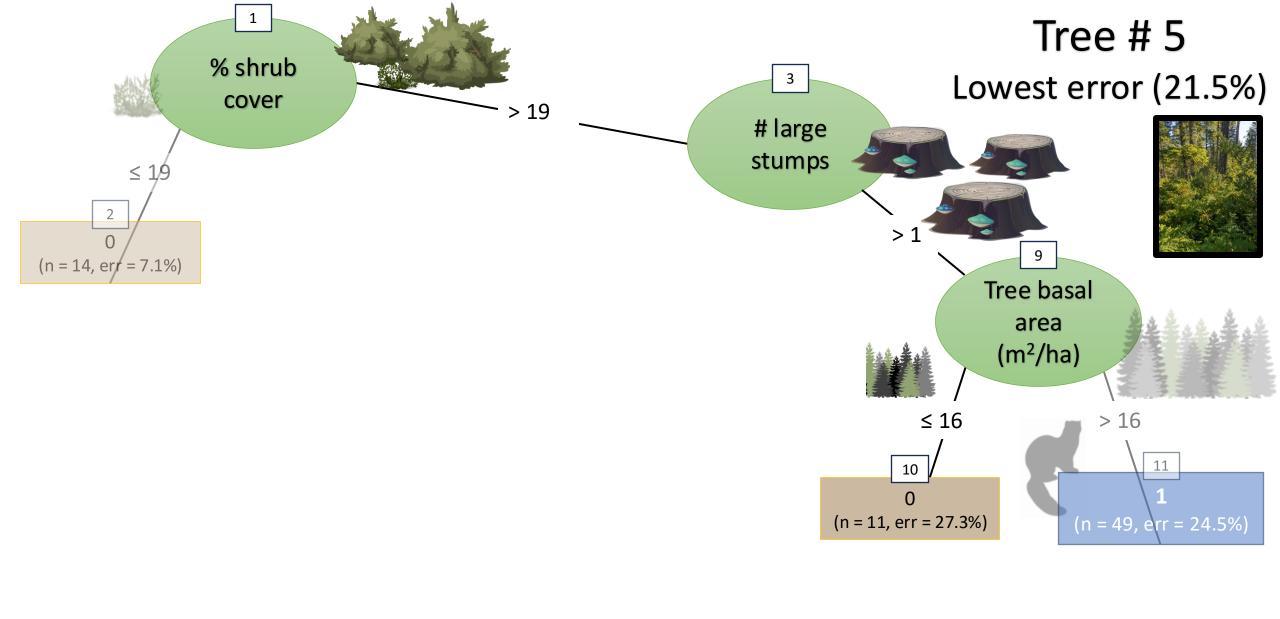


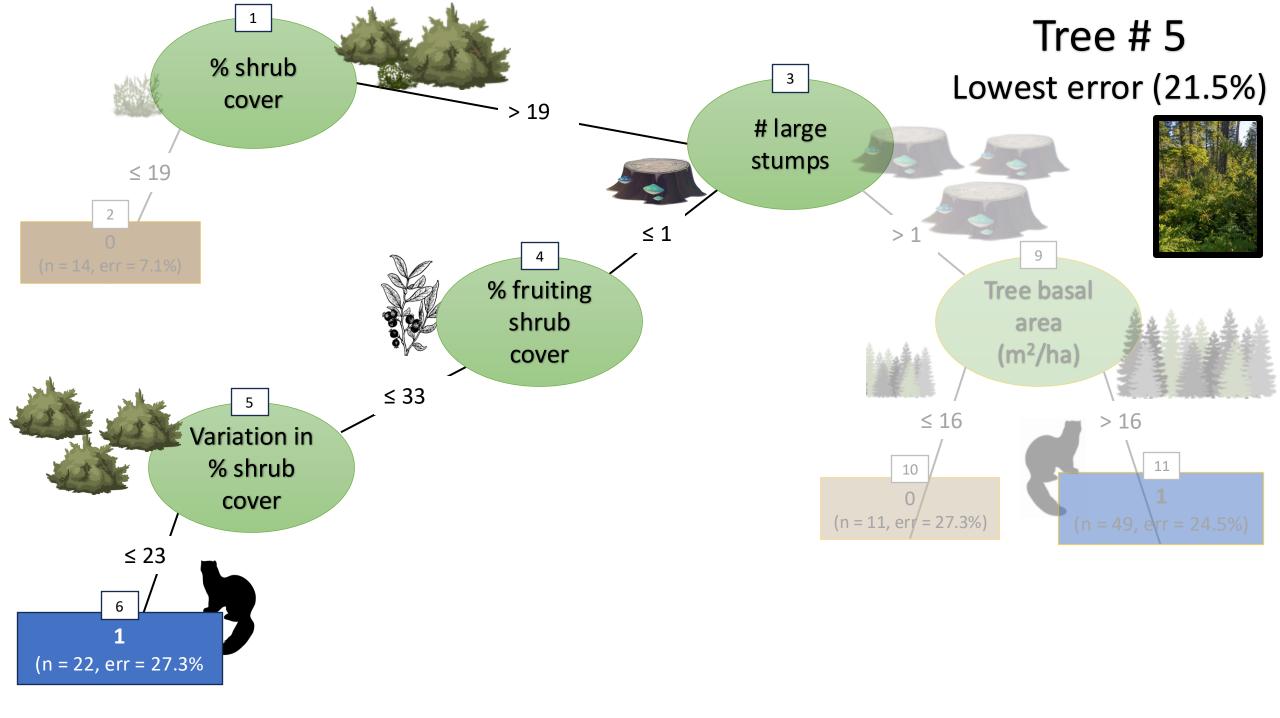


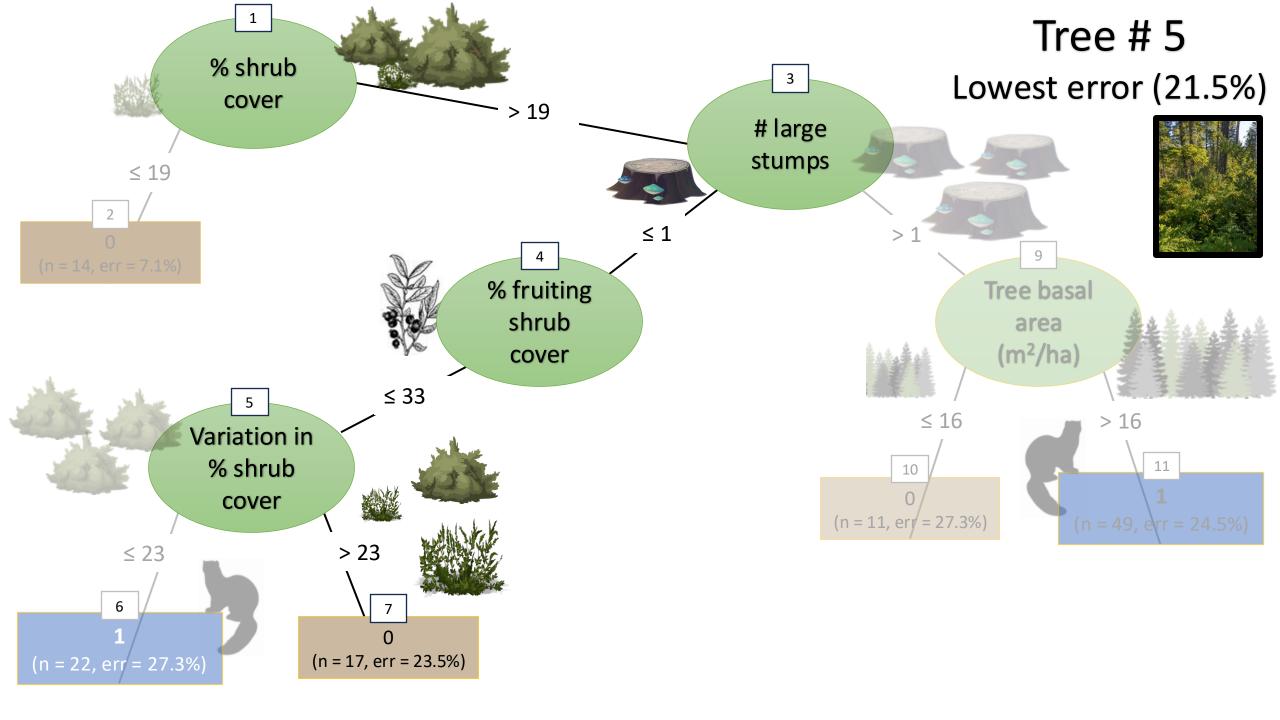
Tree # 5 Lowest error (21.5%)

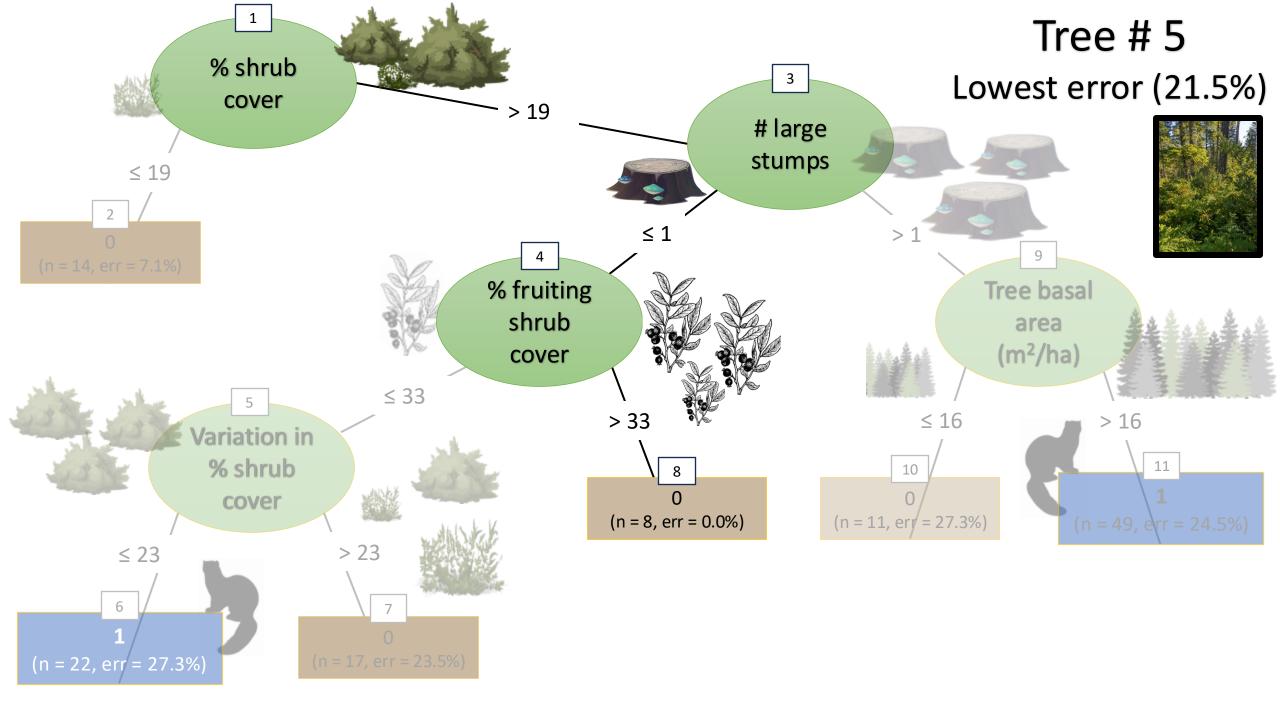


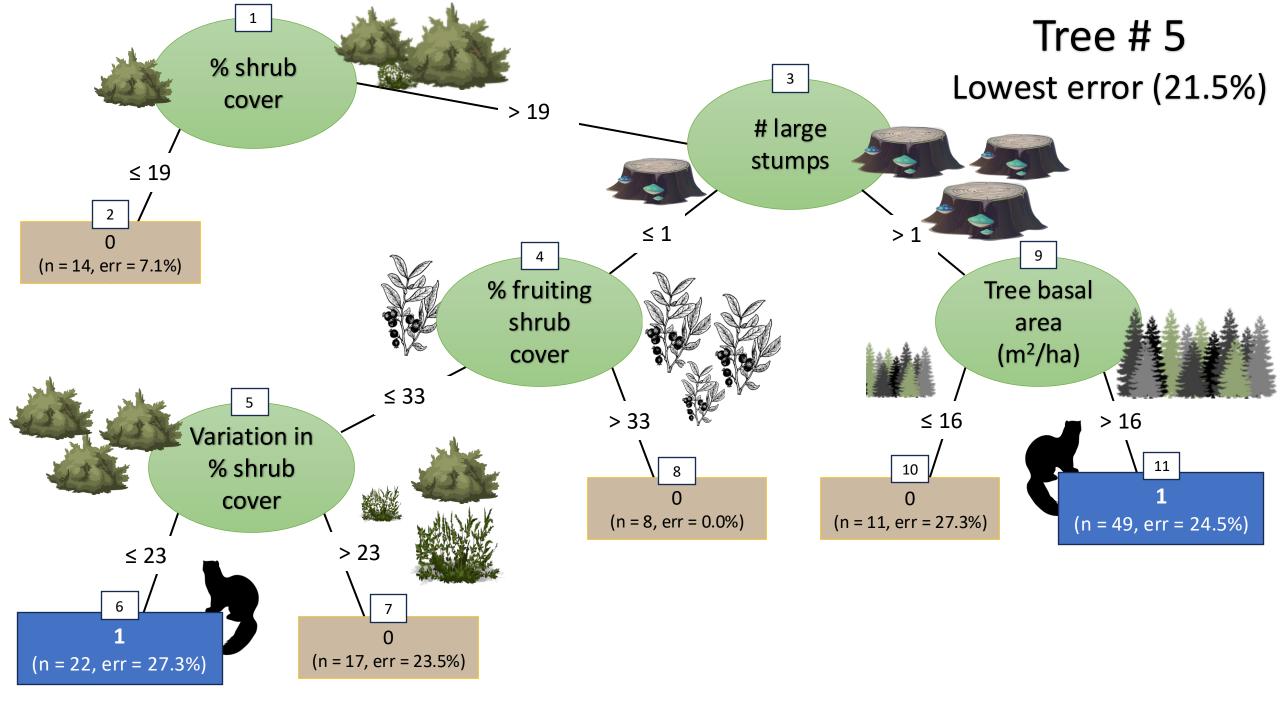






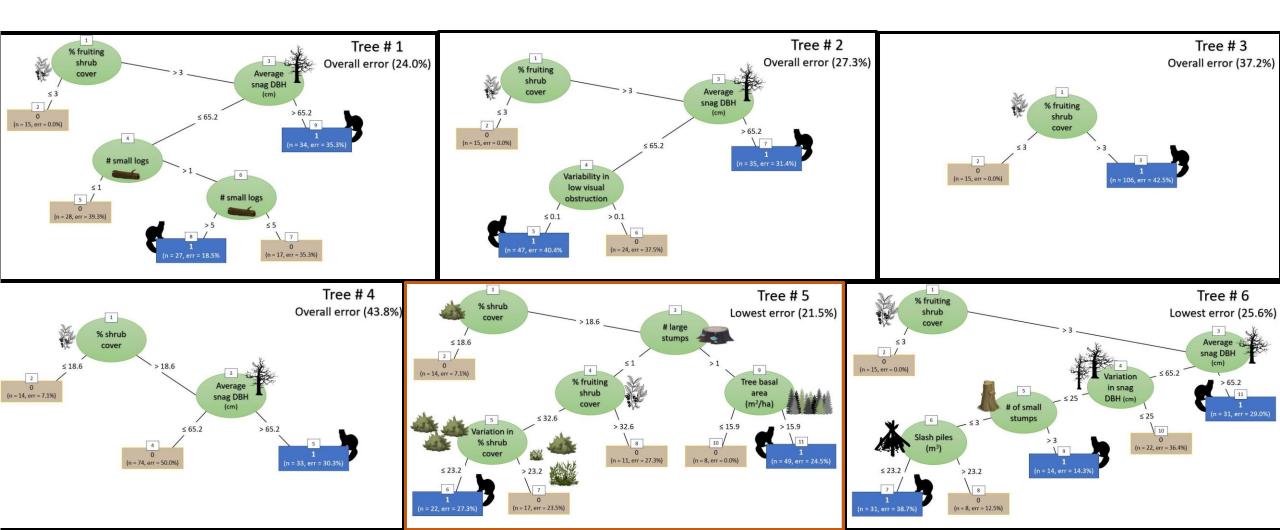




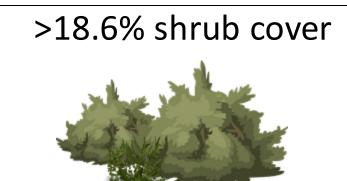


Example from Southern Oregon

Retained 22/40 variables for final modeling 11/22 variables appeared in 6 final trees



Southern Oregon marten resting conditions:*



>3% fruiting shrub cover



>65.2 cm DBH snags



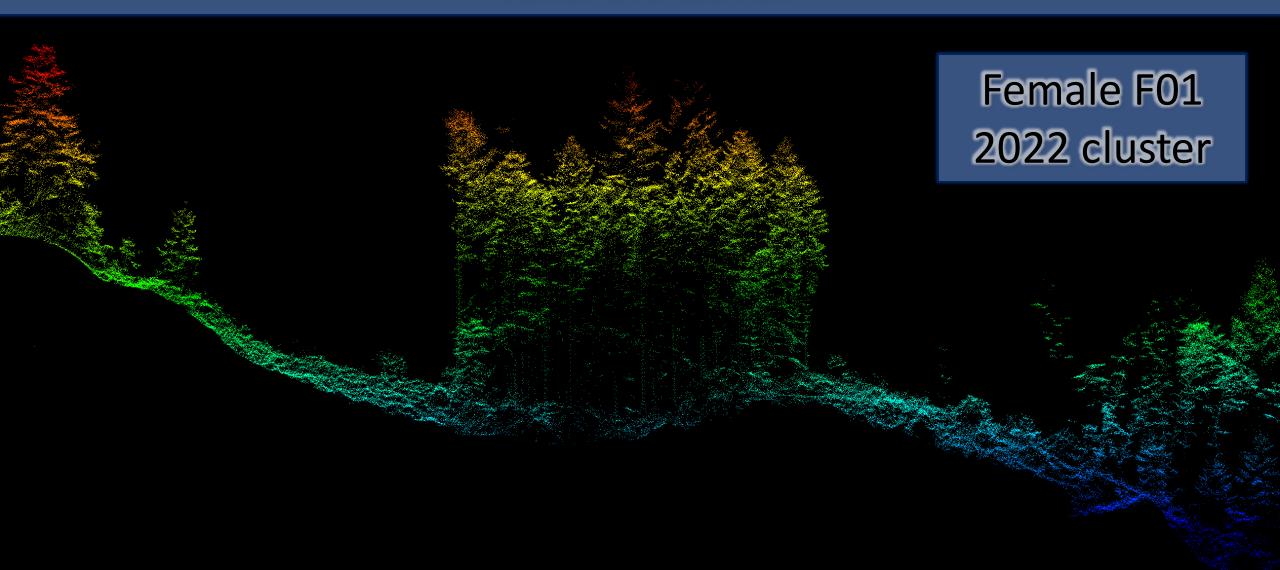
*when used in context of decision trees



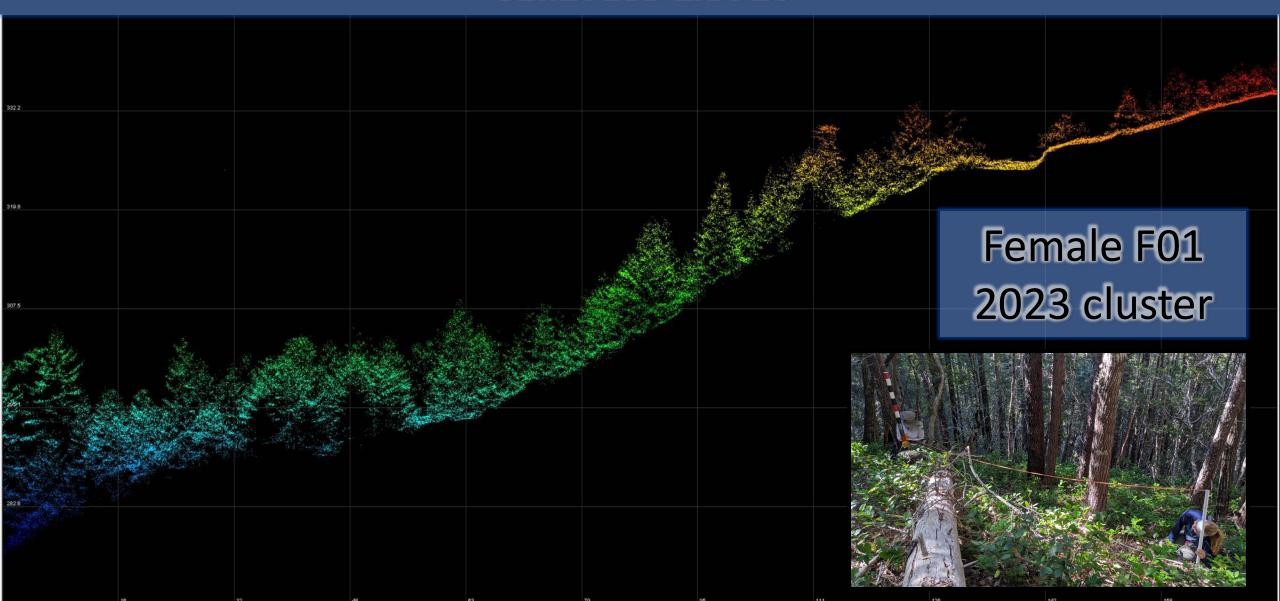




Bonus 1: Using detailed field-based plot measurements to calibrate LiDAR

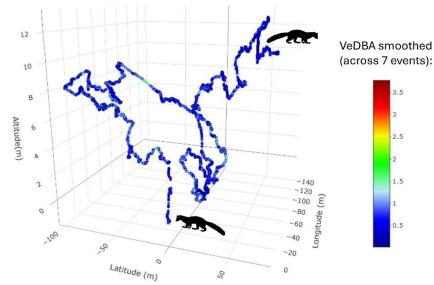


Bonus 1: Using detailed field-based plot measurements to calibrate LiDAR













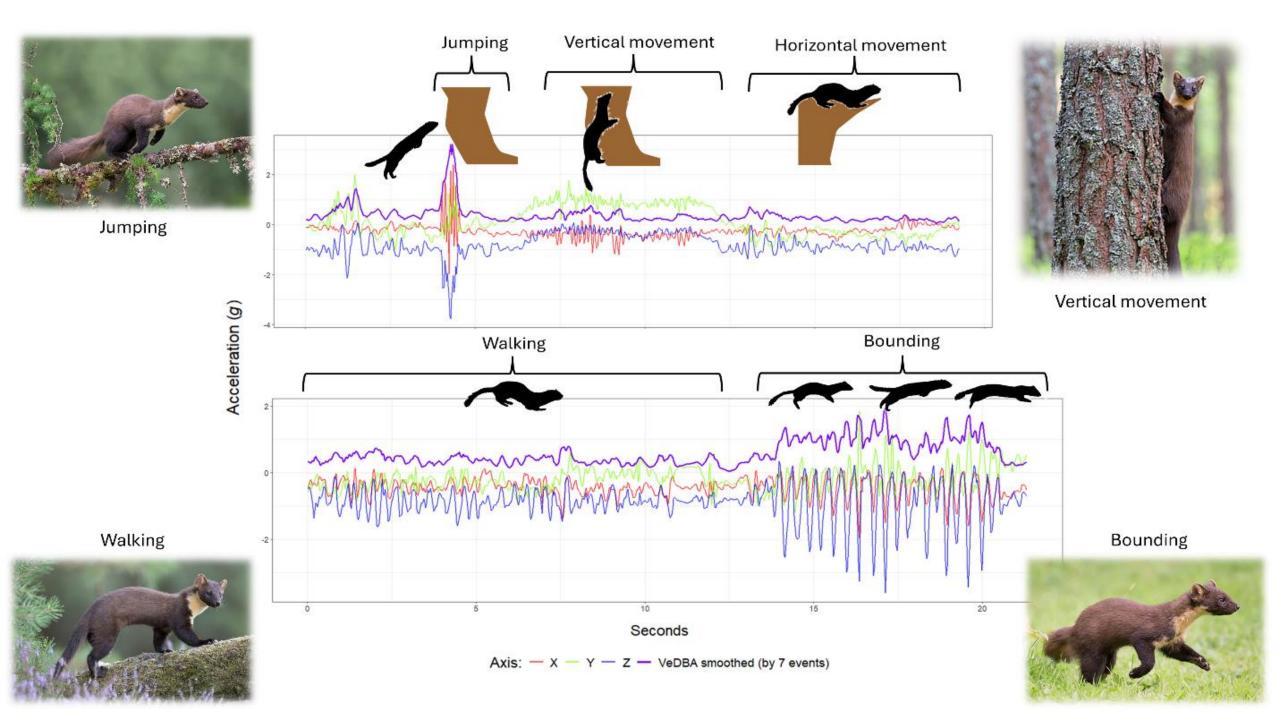


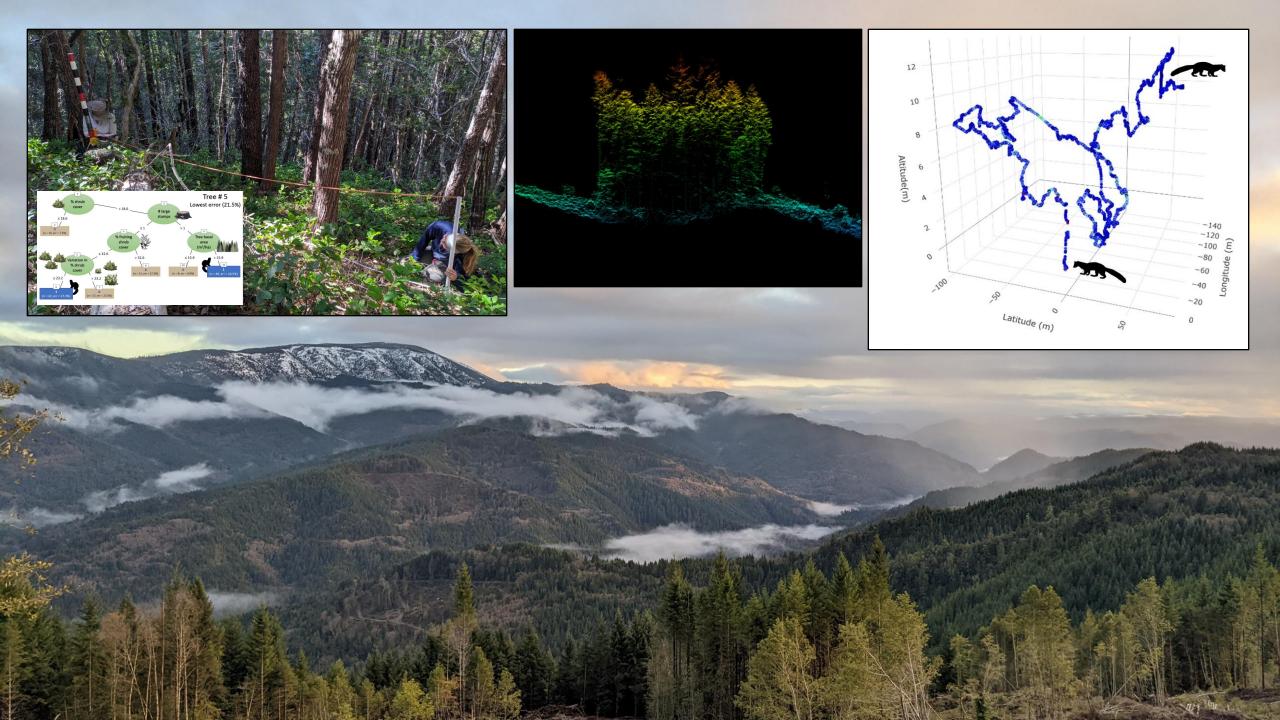




IMPACT. SCIENCE. SOLUTIONS.

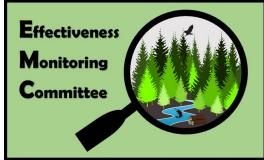








Thank you!!!

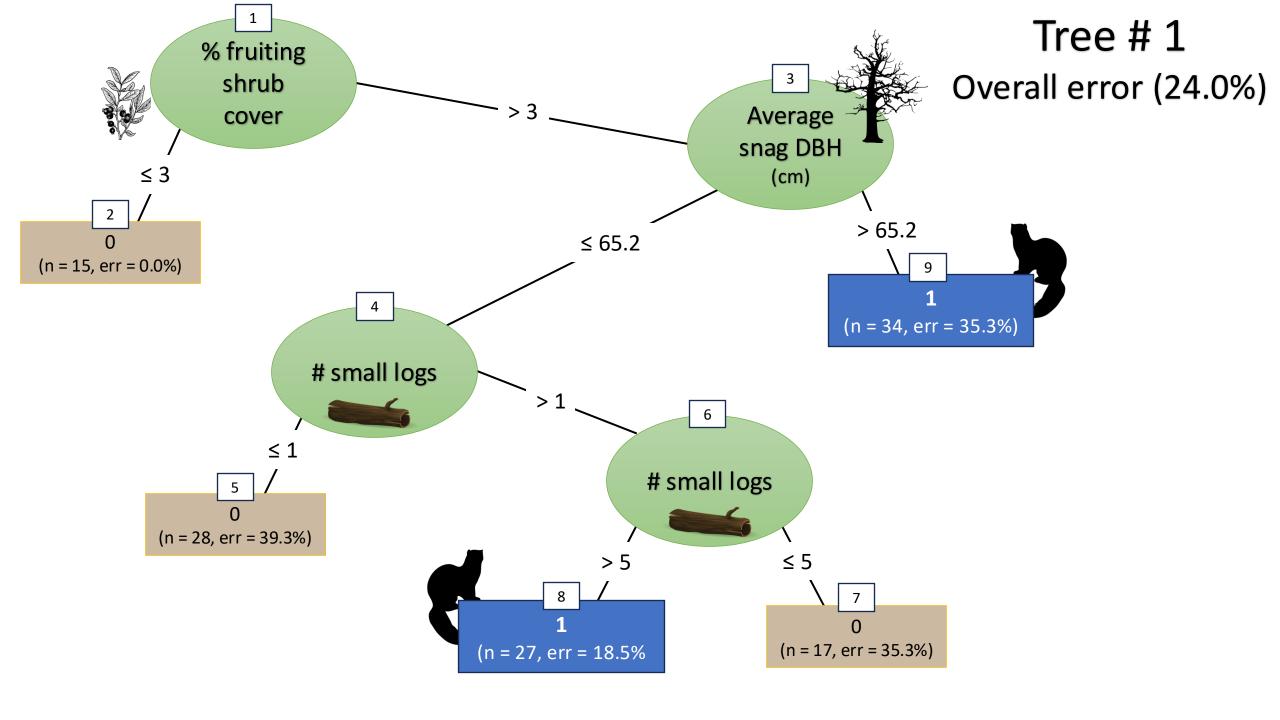


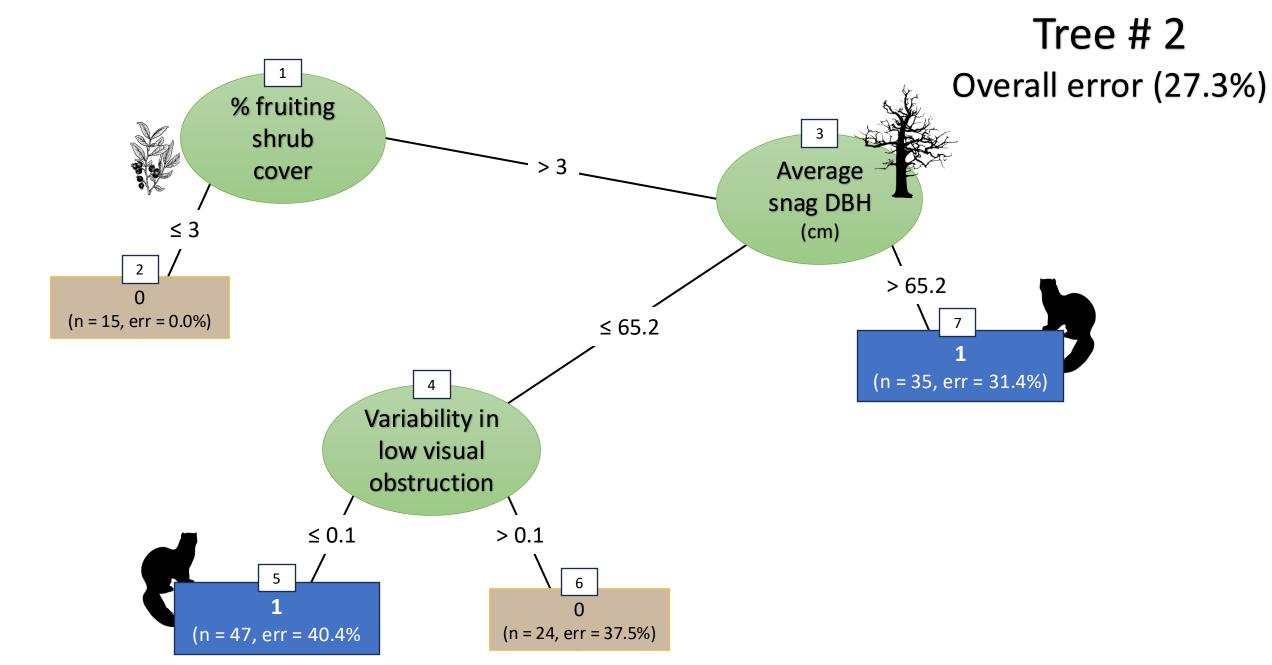




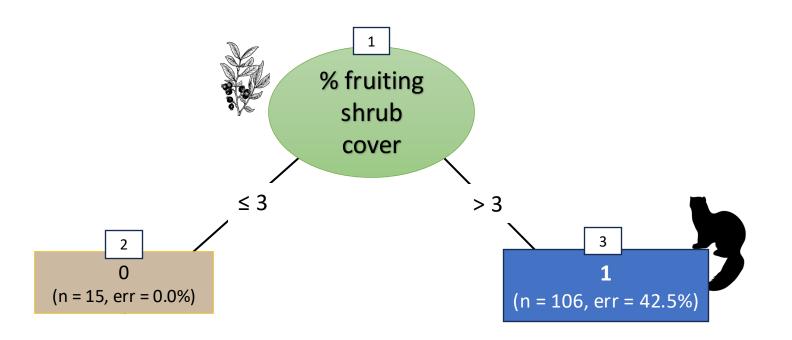








Tree # 3
Overall error (37.2%)



Tree # 4
Overall error (43.8%)

